# **COSME:** a framework for agile manufacturing systems

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COSME is a software platform which allows to design, build and execute distributed control applications. COSME was initially born under the requirements of the company TUROMAS, a glass cutting and handling machine tools manufacturer for over 20 years (www.turomas.com). It is the platform TUROMAS is using for the development of their new generation of products.

COSME is still not a full implementation of the IEC 61499 standard, although it uses some of its concepts: (a) Component based programming (FB-Types) (b) Applications created composing FB networks (c) Distributed system (FB networks can be spread across various controllers), and (d) Reconfigurability (FBs can be substituted from the FB network on the fly), so, COSME allows to develop control software for agile manufacturing.

On the other hand, its main defining characteristics are the following: (a) Predefined events in all FB-types. The COSME execution model assumes the existence of those predefined events, and ensures the code execution in a sequential fashion, which gives, as a result, a predictable and reproducible behavior, in a simpler and scalable implementation. (b) Predefined communication types allow designers to avoid dealing with the communication details. As a result, connections across controllers become much more transparent and straightforward.

COSME is still under development and it is not intended to become a commercial product. It will be released as open source software. COSME fits well to machine tools design requirements but it is flexible enough to be used in other application domains.

# COSME: a framework for agile manufacturing systems

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**TUROMAS Group** 

# Motivation

- TUROMAS: 20 years of experience
- Outdated technology :
  - MS-DOS, no Network, obsolete GUI, no USB, ...
  - "Guru" multifaceted engineer needed
- Needs detected:
  - Open+Standard platforms: RTOS, Network, Windows-like GUI
  - $\downarrow$  development costs
  - $\downarrow$  guru dependance
  - ↑ customer perceived quality
  - Add non-functional requirements
    - Integration with Enterprise Information Systems (MES, ERP...)
    - Preventive/Predictive maintenance, Fault Management
- Got interested in:
  - Component orientation
  - Reusability & reconfigurability -> Agile manufacturing
  - Distributed control
    - → From machine tools to manufacturing cell/lines

Technologies considered for the new generation of products

- PLCs with IEC 61131 (not enough)
- IEC 61499 looks the obvious choice
   Commodity IEC 61499 PLCs?: still not
- Go ahead with COSME
  - Build our own "thing" to fit our needs
  - IEC 61499 looks great, but:
    - Full implementation is hard
    - Didn't need a full implementation
    - → COSME is a partial implementation of IEC 61499

## A success case

COSME framework:

coming soon... to a machine tool near you!

# Requeriments

- Cutting glass machine tools / machining lines
  - Numeric control
    - Up to 11 axes, 1 ms cycle time, better than 1mm precision, accelerations up to 22m/s<sup>2</sup>
  - PLC like
    - About 50 automatic sequences
  - I/O field buses
  - Integration with information systems
  - Value added functionalities
  - Distributed control
    - Loose coupling between line elements: cutting tables, loaders, storages, ...

### COSME particularities

	IEC 61499	IEC 61499 COSME approach
FB model	Event driven. Designers define event and data I/O, and ECC	Event driven. Predefined event I/O and ECC (normal/failure operation, initialization, etc.). Designers define data I/O
Execution models	FB invocation: Sequential or cyclic; Execution contexts: FB, resource or event chain; NPMTR (FBRT); parallel	Daisy chain (based on event chain model)
Distributed FBN	Designers must deal with the details (e.g. SIFB, FBN modifications caused by synchronization issues)	Transparent to designers (see next slide)
SFCs	Not considered	Designers can define SFCs for each FB-Type
Language	IEC 61131, Java	C (present), IEC 61131 FBD (future)
Implementation	Harder	Simpler
Scalabity	Application dependent	Good
Scope domain	General	Limited

# **Communicating machine tools**

Applicati control				COSME Daisy chain		nain	Remarks
Process of Process comman Process				COLD_INIT, WARM_INIT, FINALIZE, FAILURE, FAILURE RECOVERY			No associated data
synchror	Proce	ss control		NORM	IAL_RT, E	XT_EVENI	Associated data
HMI Aplicatio	Process command & synchronization Data management			NORMAL_NRT, BACKGROUND, BACKGROUND_REQ		EQ	Associated data
manageri	lent						
Productic managen		Few seconds	Cyclic-d	lriven	Yes	MBytes	Communication with Manufacturing Execution Systems (MES)

# **COSME** workflow

- 1. Create FB-Types, when necessary
  - Define data input/outputs, internal variables
  - Define actions (normal/failure operation, initialization, etc.)
  - Define SFCs

#### 2. Create the FB network

- Instantiate FB-Types
- Define connections only between data inputs and outputs (not necessary for events)
- Define FBs execution order
- 3. Generate code, compile and deploy
- 4. Debug the application with provided tools

# A simplified COSME application



# A simplified COSME application



#### 1/0

	MACHINE TOOL			
pplication control			FB_HMI	
rocess nchronization/HMI	E_COLD_INIT E_WARM_INIT E_FINALZE E_NORMAL_RT E_NORMAL_NRT E_EXT_EVENT	EO_COL_INIT EO_WARM_INIT EO_FINALIZE EO_NORMAL_RT EO_NORMAL_NRT EO_DEXT_EVENT EO_BACKGROUND		



# A real COSME application

#### Complexity

- □ ≈ 35 FB-types, 200 instances
- □ ≈ 70 SFCs
- 2 CANopen field bus
- $\approx$  128 digital I/O
- I1 encoders
- 1 ms cycle time (RT), 20 ms cycle time (distributed non-RT)
- Windows-like HMI, integration with MES
- Running on
  - I B&R AutomationPC 620 (celeron type industrial PC)
  - RTAI (Linux Real Time) + Java

# The elements of the COSME framework

COSME DC S EMCOS Domiciano v 2.0.4	🖌 New Variable	
File Edit View Generate Options Help	Name: workingTime Type: double	COSME runtime
Cart0     C	Initial Value: 0.0 Unit: h	Domiciano IDE
COS sistema_habilitado c1_1.variable2 COS start_tareas_periodi c1_1.variable3 stop_tareas_periodi c1_1.variable3 stop_tareas_periodi c1_1.variable3	✓ Registrable             ✓ Public             ✓ Public	Arcadio comms library
1     funcion_normal1     c1_1variable5       -     funcion_normal2     c1_1variable5       -     funcion_normal2     c1_1variable5       -     funcion_normal     c1_1variable5       2     -     funcion_normal       5     -     funcion_normal       c1_1_icido1     c1_1icido2	Editable         Configurable         Reserved         Aux. Var:         workingTime_enable         Maintenance Actions	<ul> <li>HMI</li> <li>Interaction with external applications (MES, ERP)</li> </ul>
<ul> <li>max</li> <li>min</li> <li>min</li> <li>min</li> <li>min</li> <li>min</li> <li>min</li> <li>min</li> <li>sistema</li> <li>sistema_max</li> <li>min</li> </ul>	==> Choose one       10005   Compressed air filter change       11001   Fan axes alignment check       Delete     Add	
B - Cestas Muestreadores Grafcets	Maintenance Level Limits:         Information:       9500.0         Action Expected:       10000.0         Critical:       15000.0	A 250M 375M 500M 622 Máximo Minimo Cursor EscaladMáximo Minimo
	Array	
9. Messages Output Debug Reading names list from file 'C:\Users\ccatalan\blas_r 'C:\Users\ccatalan\blas_nombres.xml: 203 names. Connecting with 155.210 Mounting Sambarum Cosme directory is in C:lencos Launidat / zet concetada a\U55.210	Dimension Elements number +	

# Where can

- Still not for sa
- In fact
   It will be available

# Interested? Let's talk! E-mail: fserna@unizar.es Skype: uz\_fserna

- Organizations
  - feeding COSME with vectors to help steer its development...
  - ...are welcome